

Supplementary Data 2.—In order to calculate the vertical component of drag,  $D_v$ , a modified version of Eq. 9 was developed that accounts for the starting position of the arm relative to vertical,  $\alpha$ , and the angle through which the arm rotates,  $\theta$ , the latter of which affects the angular velocity of the arm,  $\omega$ . The instantaneous vertical component of thrust is found via trigonometry as:

$$D_{Vinst} = D_{Tinst}\sin(\alpha) \quad (10)$$

To get total vertical thrust, Eq. 10 is integrated with respect to time during the translation of the arm from the start of the power stroke to its completion, from  $t=0$  to  $t=t$ :

$$D_V = \int_0^t D_T \sin(\alpha) dt \quad (11)$$

$$D_V = D_T \int \sin(\omega t) \quad (12)$$

$$D_V = D_T \left( -\frac{\cos(\alpha)}{\omega} + \frac{\cos(\alpha + \theta)}{\omega} \right) \quad (13)$$

Eq. 13 is slightly rewritten in the text as Eq. 4, and is the model's analytical solution.